

## IEEE 1914 NGFI Partial Timing Support (PTS) in NGFI

Yongfang Xu, Nokia Shanghai Bell

4-6 December 2018

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Partial Timing Support in NGFI

### IEEE 1914 Next Generation Fronthaul Interfaces Jinri Huang, HuangJinri@ChinaMobile.com

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<b>Date:</b> 2018-12-04			
Author(s):			
Name	Affiliation	Phone [optional]	Email [optional]
Yongfang XU	Nokia Shanghai Bell		

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## **PTS requirements in IEEE P1914.1**

- IEEE P1914.1/D3.0 has such requirements in section 8.5.2 and 9.3.1:
  - In section 8.5.2 (NGFI Requirements):
    - One of the following PTP profiles shall be used for NGFI network time distribution, with the optional exceptions that are listed henceforth:
      - *a)* **ITU-T G.8275.1 PTP Telecom Profile** for Phase/Time Synchronization with Full Timing Support from the Network.
      - *b) ITU-T G.8275.2 PTP Telecom Profile* for Phase/Time Synchronization with Partial Timing Support from the Network.
  - In section 9.3.1 (FTN Requirement):
    - For packet-based time distribution, an FTN shall support at least one of the following PTP profiles, with the optional exceptions that are listed henceforth:
      - *a) ITU-T G.8275.1 PTP Telecom Profile* for Phase/Time Synchronization with Full Timing Support from the Network.
      - **b) ITU-T G.8275.2 PTP Telecom Profile** for Phase/Time Synchronization with Partial Timing Support from the Network.

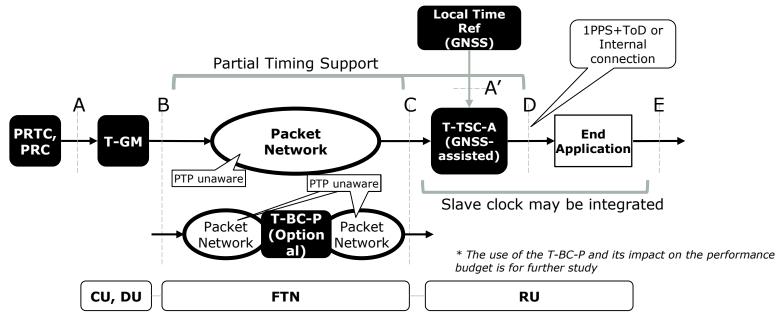


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# Partial Timing Support (PTS) (1 of 2)

Per G.8271.2, PTS is composed of two cases:

- Assisted Partial Timing Support (APTS)
  - PTP is used as a backup timing source to a local timing reference (e.g., PRTC+GNSS) for durations up to 72h. It is not intended to use PTP as the primary timing source

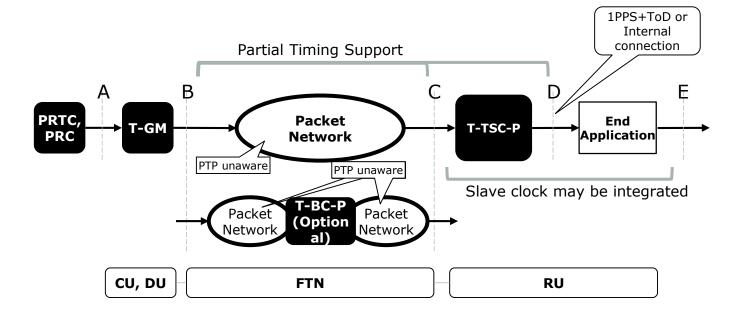




# Partial Timing Support (PTS) (2 of 2)

Partial Timing Support (PTS)

• PTP is used as the primary source of time to the end application.



\* The use of the T-BC-P and its impact on the performance budget is for further study



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## Why PTS or APTS?

- Compared with the solution of GNSS populated at every eNB, PTS/APTS can solve GNSS antenna line of sight (LoS) problem, especially for the deployment in "urban canyon"
- Compared with deploying new equipment with T-BC embedded, PTS/APTS can support time/phase distribution in existing packet network without PTP support, which avoids an onerous network investment cycle
- Compared with deploying distributed (lite) PRTC, APTS can provide higher (holdover) performance when the PRTC loses accurate GNSS connectivity



## PTS(APTS) vs. FTS

- Compared with the solution of GNSS populated at every eNB, PTS/APTS can solve GNSS antenna line of sight (LoS) problem, especially for the deployment in "urban canyon"
- Compared with deploying new equipment with T-BC embedded, PTS/APTS can support time/phase distribution in existing packet network without, which avoids an onerous network investment cycle
- Compared with deploying distributed (lite) PRTC, APTS can provide higher (holdover) performance when the PRTC loses accurate GNSS connectivity



- FTS can provide same feature to deliver time/phase synchronization over network
- According to G.8271.2, PTS currently only considers the applications corresponding to the class 4 (1.5us)
- FTN is a time-sensitive network. PTS can't provide determinative time sync performance, as its performance heavily relies on the PDV performance of the PTP-unaware Nes
- FTS has well defined noise model in each node (cTE, dTE) and formula to calculate accumulated noise of a FTS clock chain at network limit (RU input). This can provide guarantee performance in time/phase (for all classes) and frequency error.
- It also relates to the PRTC design, which supposes to have secondary time reference or freq reference input as backup

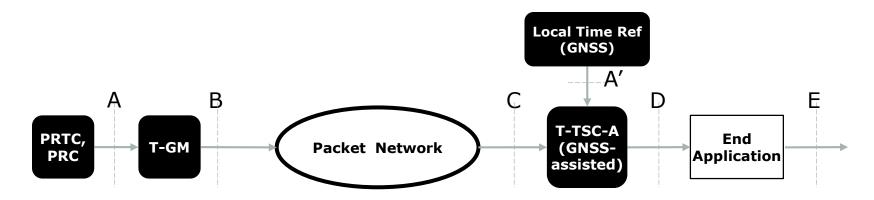


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# Network Limits defined for PTS (G.8271.2) (1 of 2)

- The network limits specified in G.8271.2 are for small, wellcontrolled networks (e.g., in-building or last-mile network segments), which can guarantee that the stringent PDV and asymmetry network limits are met.
- The necessary clock specifications for PTS are all for further study (G.8273.4 is in development in Q13/SG15), and target for class 4 in backhaul.
- The limits at the refer point C given in G.8271.2 represent the maximum permissible levels of phase/time error and noise, per the applications corresponding to the class 4 listing in Table 1 of [ITU-T G.8271], i.e. +/-1.5us

# Network Limits defined for PTS (G.8271.2) (2 of 2)



### Reference point A and A': Reference point B (integrated):

### • max $|TE| \le 100 \text{ ns}$

\* The network limit at point A' may not be applicable in all cases

### Reference point C: APTS (Type I):

- Peak-to-peak pktSelected2wayTE
  <1100 ns</li>
- Selection window = 200 s
- Selection percentage = 0.25%
- Selection method: percentile average packet selection

### PTS (Type I):

- max|pktSelected2wayTE| < 1100 ns</li>
- Selection window = 200 s
- Selection percentage = 0.25%
- Selection method: percentile average packet selection

### Reference point D: APTS (Type I):

max|TE| ≤ 1350 ns <sup>\*\*</sup>

## PTS (Type I):

FFS

\* This requirement is only applicable in case of T-TSC-A external to the end application



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## **Conclusions and Proposals**

- G.8275.2 is not designed for more stringent time/phase synchronization. Current relevant ITU recommendations are for the applications corresponding to the class 4
- The PTP-unaware part of the network using PTS requires wellcontrolled low levels of packet delay variation (PDV) and asymmetry
- Lack of specification of PTS clocks leads to indeterminate time/phase performance during the period of network planning
- PTS/APTS would not provide enough accuracy required by Category A+/A/B
- Reconsider the requirement of support of PTS in IEEE 1914.1
- At least to add notes under the requirement to restrict the PTS use case, for example, 3G and 4G backhaul



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